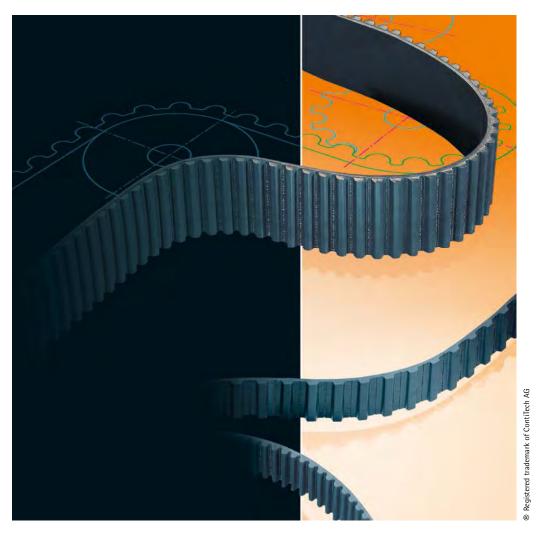
CONTI® SYNCHRODRIVE Polyurethane Synchronous Drive Belts





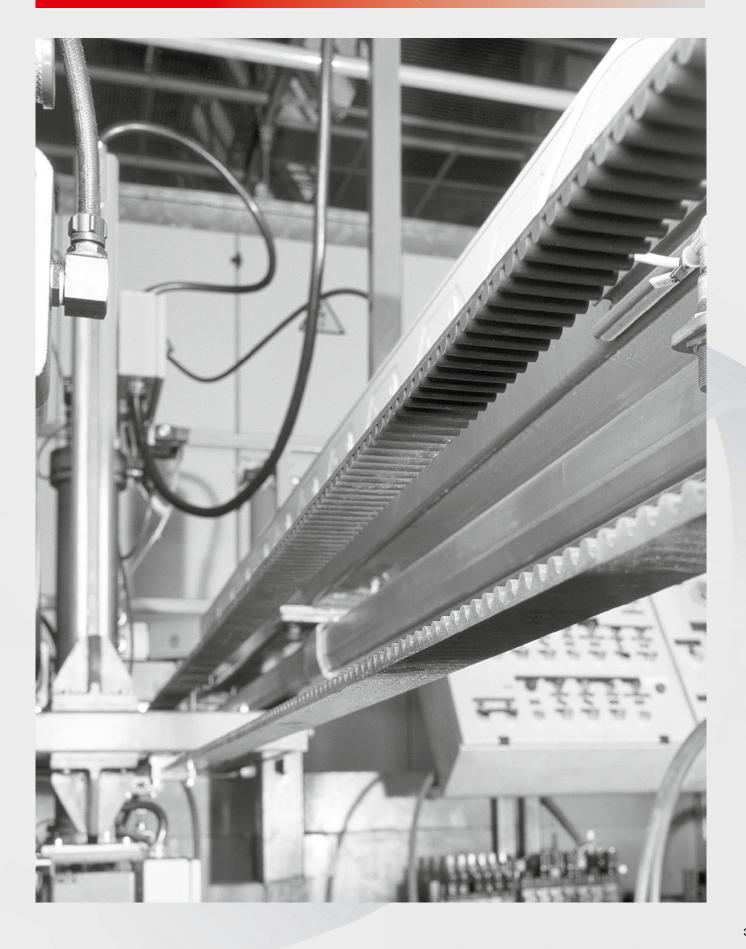


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CONTI® SYNCHRODRIVE Synchronous Drive Belts

Properties / Construction / Designation / Product range / Tolerances



CONTI® SYNCHRODRIVE Synchronous Drive Belts

CONTI® SYNCHRODRIVE Belts for synchronous transmission of rotary and linear motion

CONTI® SYNCHRODRIVE belts are power transmission products made from a highly durable polyurethane elastomer incorporating a steel-cord tension member. They are manufactured precisely to length using a newly developed production technique.

CONTI® SYNCHRODRIVE belts can be used in the openended or endless form. In all cases, they ensure that rotary motion is transmitted uniformly and with angular precision. CONTI® SYNCHRODRIVE belts permit low-cost drive designs, even where difficult operating conditions have to be taken into account. Their properties provide a highly reliable, maintenance-free solution to even the most demanding drive problems.

CONTI® SYNCHRODRIVE belts are available in 10 tooth profiles and several standard widths, covering a host of different applications involving various loads and service conditions. They are ideal for drives with a large center distance, for synchronous conveyor systems and transport devices with sliding rails as well as for positioning and reversing drives in linear and control engineering. Modern production techniques and rigorous in-process quality controls guarantee products with maximum reliability and a consistently high standard of quality.

Properties

Precise synchronism due to positive engagement

The belt teeth mesh with those of the pulley in the same manner as the teeth on a gear. This positive drive principle provides synchronous operation and eliminates speed variation.

A variety of possible applications at low design cost

CONTI® SYNCHRODRIVE belts can be used as synchronous drive or transport belts in either the open-ended or endless version. For special applications, CONTI® SYNCHRODRIVE belts can have heavy-duty profiles welded to them for indexing and conveying applications. As open-ended drive components, CONTI® SYNCHRODRIVE belts are ideal for linear and control drives that have to transmit rotary motion with repeat accuracy and multiple positioning control.

Low loads on shafts and bearings

The tooth grip principle requires only low initial belt tensioning. Thus the load on shafts and bearings is kept to a minimum.

Compact drive design

High dynamic stability and flexibility allows the use of small pulley diameters, low center distances, and belt-back idlers. This enables a lightweight, low-cost drive setup with less space requirement.

No maintenance

CONTI® SYNCHRODRIVE belts are maintenance-free; no lubrication or retensioning is required. Constant belt tension is guaranteed by the use of a high-strength steel-cord tension member.

High efficiency

The superb flexural properties of the synchronous drive belt as well as the exact dimensional mating of the belt and pulley tooth contours permit drives with an efficiency of 98%.

CONTI® SYNCHRODRIVE belts are resistant to

- wear
- oil and grease
- opetrol and benzene
- hydrolysis
- UV and ozone
- temperatures ranging from 30 °C to 80 °C (for operational temperatures outside –10 °C to 50 °C please seek advice from your Mulco sales partner)
- o can be bonded to thermoplastics

Belt versions _

CONTI® SYNCHRODRIVE belts are supplied in the following versions:

- HF high flexibility version
 all profiles except for 3 mm pitch
 e.g. for drives with small pulley diameters.
- HP high power reinforced version HTD and STD profiles, e.g. for heavy-duty control systems.
- HS high stiffness of tension member HTD and STD profiles, e.g. for high-precision linear drives.

Other special versions, e. g. aramid tension member, can be supplied on request.

- **XHP** extremely high power tensile-strength HTD 14M profile, e.g. for lifting systems.
- PAZ with polyamide fabric facing on the teeth side e.g. for sliding-rail transport systems.

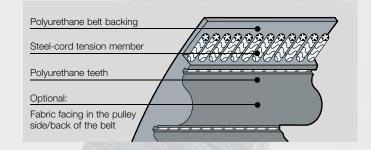
 Antistatic aPAZ version on request.
- PAR with polyamide fabric facing on the back of the belt e.g. for skid-queuing conveyors.

 Antistatic aPAR version on request.
- v endless belt in HF version and lengths from 1000 mm, all profiles except for 3 mm pitch e.g. for rotary drives with large center distances.

Construction .

Our synchronous drive belts are made up of:

- polyurethane teeth and back, color: black
- steel-cord tension member, with balanced right/left-handed cord twist



Polyurethane teeth and back

Belt teeth and back are made from a tough polyurethane elastomer with excellent adhesion to the tension member. The high wear resistance of the polyurethane ensures trouble-free drive performance and a long service life. These features are enhanced even more by the balanced layout of the tension cords.

Steel-cord tension member

Synchronous drive belts for positive drive systems must have a high resistance to elongation and a high tensile strength. Extra-strong steel tension cords, laid parallel to the belt edges, guarantee the belt's high loading capacity and accurate running properties.

CONTI® SYNCHRODRIVE Synchronous Drive Belts

Designation

member.

CONTI® SYNCHRODRIVE synchronous drive belts are specified in accordance with defined standards for the different belt types showing the pitch length, tooth pitch and belt width, plus a code for the belt version, see page 5.

- Pitch length in m
 The pitch length of the belt is the overall circumference, or length measured at the neutral pitch line.
 The pitch length is located in the middle of the tension
- Tooth pitch in mm
 The tooth pitch is the linear distance between two adjacent teeth at the pitch line.
- Belt width in mm
 The belt width and width designation are identical.

Examples	Examples:							
CONTI® SYNCHRODRIVE HTD drive belts								
M 30-8M-	50 HP							
M open-ended type								
30	pitch length 30 m							
8M	tooth pitch 8 mm , HTD profile							
50	belt width 50 mm							
HP	reinforced version							

V 2400-S	5 5M-30 HF
V	endless type
2400	belt length 2400 mm
S 5M	tooth pitch 5 mm, STD profile
30	belt width 30 mm
HF	flexible version

CONTI® SYNCHRODRIVE STD drive belts

The number of teeth is a function of pitch length and pitch:

$$z = \frac{L_{W}}{t}$$

Product range

Profiles

CONTI® SYNCHRODRIVE synchronous drive belts are manufactured in 10 profile sizes. Dimensions of HTD and STD synchronous drive belts correspond to the specifications laid down in ISO/F DIS 13050 (draft version). Table 1 on page 7 gives a summary of the profile dimensions as well as other technical information for the belts we supply. Special pulleys must be used for linear drives with high precision requirements. More information about pulleys is given in section 2 on "Pulleys" which starts on page 10.

Lengths

CONTI® SYNCHRODRIVE synchronous drive belts are available in either the open-ended or endless version.

Widths

CONTI® SYNCHRODRIVE synchronous drive belts are supplied in several standard widths. Dimensions are given in Table 2 on page 7. Other widths are available on request.

Versions

CONTI® SYNCHRODRIVE synchronous drive belts made from polyurethane with steel cords aligned parallel to the belt edges are precision-made components for applications in drive and transportation engineering. Several versions are available to meet various operating requirements. More details are given on page 4 under "Properties".

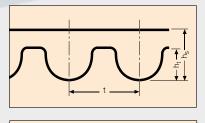
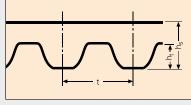


Fig. 1

Tooth profile HTD 3M, HTD 5M, HTD 8M, HTD 14M



Tooth profile STD S 5M, STD S 8M, STD S 3M on request

Table 1 Specifications										
T4		HTD				STD				
Tooth profile		3M 5M 8M 14 M				S 3M	S 3M S 5M S 8M			
Tooth pitch t	mm	3,00	5,00	8,00	14,00	3,00	5,00	8,00		
Belt thickness h _s	mm	2,40	3,60	5,60	10,00	2,30	3,40	5,20		
Tooth height h _t	mm	1,30	2,10	3,40	6,10	1,14	1,90	3,00		
Weight m _{spez} per mm	of belt width									
Type HF	10 ⁻³ kg/m		3,36	5,40	10,37		3,21	5,24		
Type HP	10 ⁻³ kg/m	3,15	4,06	6,32	11,27	3,08	3,91	6,22		
Type HS	10 ⁻³ kg/m			7,22	11,40		4,64	7,12		
Type XHP	10 ⁻³ kg/m				14,00					
Standard lengths										
Type M L _w	m				30 or 60)				

Table 2 Belt width – b in mm									
	HTD				STD				
Tooth profile	3M	5M	8M	14M	S 3M	S 5M	S 8M		
	5	5			5	5			
	10	10	10		10	10	10		
	15	15	15		15	15	15		
			20				20		
	25	25		25	25	25			
			30				30		
				40					
	50	50	50	50/55	50	50	50		
			85	85			85		
			100	100			100		
				115					
				120					
				150					

Other intermediate widths on request.

CONTI® SYNCHRODRIVE Synchronous Drive Belts

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CONTI® SYNCHRODRIVE synchronous drive belts are precision-made products. Manufacturing involves reliable process techniques and maximum accuracy throughout all stages. Deviations in length, width and thickness are subject to extremely tight tolerances.

Table 3 Belt length tolerances						
Pitch length L _w mm	Length tolerance %					
L _w	± 0,1					

Table 4 Belt width tolerances									
Tooth profile		HTD	HTD			STD			
		ЗМ	5M	8M	14 M	S 3M	S 5M	S 8M	
Belt width b	up to 25 mm	± 0,5	± 0,5	± 0,6	± 0,6	± 0,5	±0,5	±0,6	
	> 25-50 mm	± 0,6	± 0,6	± 0,7	± 1,0	± 0,6	±0,6	±0,7	
	> 50 mm			± 0,8	± 1,2			±0,8	

Table 5 Belt thickness tolerances (Type M)									
Tooth profile		HTD				STD			
		3M	5M	8M	14 M	S 3M	S 5M	S 8M	
Belt thickness h _s	mm	2,4	3,6	5,6	10	2,3	3,4	5,2	
Thickness tolerance	mm	±0,25	± 0,25	± 0,4	±0,6	± 0,25	± 0,25	± 0,4	



Pulleys

Designation / Minimum number of teeth / Diameters / Tolerances / Clamping length



Pulleys

Pulleys

Precise belt/pulley conformance is vital to ensure accurate power transmission as well as smooth operation and a long service life for synchronous belt drives.

ContiTech engineers have modified pulley tooth-gap profiles so that they conform ideally to the respective belt profiles.

Use of these optimized pulleys is recommended especially for CONTI® SYNCHRODRIVE HTD belts.

Pulleys with optimized profiles are obtainable from your Mulco sales partner.

Linear drives with demanding positioning requirements need pulleys with minimized gap clearance. If you are planning a special drive design, please consult our application engineers for advice.

Designation

Pulleys for CONTI® SYNCHRODRIVE belt drives are identified in accordance with the standards defined for the various belt types by their number of teeth, tooth pitch and pulley width, as well as a code denoting the type of pulley.

- P General designation for toothed pulleys.
- Number of teeth The pulley's number of teeth is calculated from the pitch circumference and the pitch:

$$z = \, \frac{U_W}{t} \, = \, \, \frac{\pi \cdot d_W}{t}$$

pulley.

Tooth pitch in mm
The tooth pitch of the pulley is the distance between
two reference points on adjacent teeth at the circumference of the pitch diameter. The pitch diameter is larger
than the outside diameter of the pulley by double the
thickness at which the pitch line of belt rides above the

Pulley width in mm

The width designation defines the exact width of the corresponding synchronous drive belt, and not that of the pulley.

Flanged pulley data

F stands for pulleys that are flanged on both sides. Flanged pulleys prevent the belt from riding off. At least one pulley with two flanges must be used and generally, for economy, the smaller pulley of a drive is the flanged pulley. It is also possible to provide each pulley with one flange on alternate sides.

Exam	Examples:							
HTD	HTD Pulley – P 36 – 8M – 40							
Р	Designation for toothed pulley							
36	36 teeth							
8M	8 mm tooth pitch, HTD profile							
40	Pulley designation for a 40 mm wide							
	synchronous drive belt							

STD P	Pulley – P 48 – S 5M – 30
Р	Designation for toothed pulley
48	48 teeth
S 5M	5mm tooth pitch, STD profile
30	Pulley designation for a 30 mm wide
	synchronous drive belt

Minimum number of teeth

Drives fitted with CONTI® SYNCHRODRIVE synchronous drive belts should have pulleys that meet the specified minimum number of teeth. Table 6 shows the minimum number of teeth z_{min} and the minimum pitch diameter $d_{\text{w min}}$ for pulleys as well as the minimum diameter d_{min} for inside and outside idlers that are to be considered when designing a drive. Inside idlers should be toothed pulleys.

Table 6 Minimum number of teet	h / - z _{min}									
T#		HTD				STD				
Tooth profile				ЗМ	5M	8M	14M	S 3M	S 5M	S 8M
Minimum number of teeth z _{min}										
Туре	HF				12	16	18		12	16
	HP			20	16	20	26	20	16	20
	HS					28	30		24	28
	XHP						34			
Minimum pitch Ø d _{w min}										
Туре	HF		mm		19,10	40,74	80,21		19,10	40,74
	HP		mm	19,10	25,46	50,93	115,86	19,10	25,46	50,93
	HS		mm			71,30	133,69		38,20	71,30
	XHP		mm				151,52			
Minimum Ø of idler d _{min}										
Туре	HF	inside	mm		19,10	40,74	80,21		19,10	40,74
		outside	mm		30,00	60,00	120,00		30,00	60,00
	HP	inside	mm	19,10	25,46	50,93	115,86	19,10	25,46	50,93
		outside	mm	30,00	50,00	100,00	160,00	30,00	50,00	100,00
	HS	inside	mm			71,30	133,69		44,56	71,30
		outside	mm			120,00	180,00		80,00	120,00
	XHP	inside	mm				151,52			
		outside	mm				200,00			

Minimum diameter Belt version V with omega pulley configuration: please call for technical support.

Pulleys

Diameters -

Number of teeth, pitch and outside diameter of pulleys for drives fitted with CONTI® SYNCHRODRIVE belts are contained in Tables 7 to 13 (pages 12 to 15).

Table 7	•	Pulleys for CONTI® SYNCHRODRIVE HTD synchronous drive belts I mm tooth pitch, 3M profile (measurement in mm)											
Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of Teeth z	Pitch diameter d _w	Outside diameter d _a	Number of Teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a		
20	19,10	18,34	35	33,42	32,66	50	47,75	46,99	65	62,07	61,31		
21	20,05	19,29	36	34,38	33,62	51	48,70	47,94	66	63,03	62,27		
22	21,01	20,25	37	35,33	34,57	52	49,66	48,90	67	63,98	63,22		
23	21,96	21,20	38	36,29	35,53	53	50,61	49,85	68	64,94	64,18		
24	22,92	22,16	39	37,24	36,48	54	51,57	50,81	69	65,89	65,13		
25	23,87	23,11	40	38,20	37,44	55	52,52	51,75	70	66,85	66,09		
26	24,83	24,07	41	39,15	38,39	56	53,48	52,72	71	67,80	67,04		
27	25,78	25,02	42	40,11	39,35	57	54,43	53,67	72	68,75	67,99		
28	26,74	25,98	43	41,06	40,30	58	55,39	54,63					
29	27,69	26,93	44	42,02	41,26	59	56,34	55,58					
30	28,65	27,89	45	42,97	42,21	60	57,30	56,54					
31	29,60	28,84	46	43,93	43,17	61	58,25	57,49					
32	30,56	29,80	47	44,88	44,12	62	59,21	58,45					
33	31,51	30,75	48	45,84	45,08	63	60,16	59,40					
34	32,47	31,71	49	46,79	46,03	64	61,12	60,36					

Table 8	Table 8 Pulleys for CONTI® SYNCHRODRIVE HTD synchronous drive belts 5 mm tooth pitch, 5M profile (measurement in mm)											
Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	
12	19,10	17,96	28	44,56	43,42	44	70,03	68,89	60	95,49	94,35	
13	20,69	19,55	29	46,15	45,01	45	71,62	70,48	61	97,08	95,94	
14	22,28	21,14	30	47,75	46,61	46	73,21	72,07	62	98,68	97,54	
15	23,87	22,73	31	49,34	48,20	47	74,80	73,66	63	100,27	99,13	
16	25,46	24,32	32	50,93	49,79	48	76,39	75,25	64	101,86	100,72	
17	27,06	25,92	33	52,52	51,38	49	77,99	76,85	65	103,45	102,31	
18	28,65	27,51	34	54,11	52,97	50	79,58	78,44	66	105,04	103,90	
19	30,24	29,10	35	55,70	54,56	51	81,17	80,03	67	106,63	105,49	
20	31,83	30,69	36	57,30	56,16	52	82,76	81,62	68	108,23	107,09	
21	33,42	32,28	37	58,89	57,75	53	84,35	83,21	69	109,82	108,68	
22	35,01	33,87	38	60,48	59,34	54	85,94	84,80	70	111,41	110,27	
23	36,61	35,47	39	62,07	60,93	55	87,54	86,40	71	113,00	111,86	
24	38,20	37,06	40	63,66	62,52	56	89,13	87,99	72	114,59	113,45	
25	39,79	38,65	41	65,25	64,11	57	90,72	89,58				
26	41,38	40,24	42	66,85	65,71	58	92,31	91,17				
27	42,97	41,83	43	68,44	67,30	59	93,90	92,76				

Table 9	Table 9 Pulleys for CONTI® SYNCHRODRIVE HTD synchronous drive belts 8 mm tooth pitch, 8M profile (measurement in mm)												
Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a		
16	40,74	39,37	31	78,94	77,57	46	117,14	115,77	61	155,34	153,97		
17	43,29	41,92	32	81,49	80,12	47	119,68	118,31	62	157,88	156,51		
18	45,84	44,47	33	84,03	82,66	48	122,23	120,86	63	160,43	159,06		
19	48,38	47,01	34	86,58	85,21	49	124,78	123,41	64	162,97	161,60		
20	50,93	49,56	35	89,13	87,76	50	127,32	125,95	65	165,52	164,15		
21	53,48	52,11	36	91,67	90,30	51	129,87	128,50	66	168,07	166,70		
22	56,02	54,65	37	94,22	92,85	52	132,42	131,05	67	170,61	169,24		
23	58,57	57,20	38	96,77	95,40	53	134,96	133,59	68	173,16	171,79		
24	61,12	59,75	39	99,31	97,94	54	137,51	136,14	69	175,71	174,34		
25	63,66	62,29	40	101,86	100,49	55	140,06	138,69	70	178,25	176,88		
26	66,21	64,84	41	104,41	103,04	56	142,60	141,23	71	180,80	179,43		
27	68,75	67,38	42	106,95	105,58	57	145,15	143,78	72	183,35	181,98		
28	71,30	69,93	43	109,50	108,13	58	147,70	146,33					
29	73,85	72,48	44	112,05	110,68	59	150,24	148,87					
30	76,39	75,02	45	114,59	113,22	60	152,79	151,42					

Table 10	Table 10 Pulleys for CONTI® SYNCHRODRIVE HTD synchronous drive belts 14 mm tooth pitch, 14M profile (measurement in mm)											
Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	
18	80,21	77,41	33	147,06	144,26	48	213,90	211,10	63	280,75	277,95	
19	84,67	81,87	34	151,52	148,71	49	218,36	215,56	64	285,20	282,40	
20	89,13	86,33	35	155,97	153,17	50	222,82	220,02	65	289,66	286,86	
21	93,58	90,78	36	160,43	157,63	51	227,27	224,47	66	294,12	291,32	
22	98,04	95,24	37	164,88	162,08	52	231,73	228,93	67	298,57	295,77	
23	102,50	99,70	38	169,34	166,54	53	236,18	233,38	68	303,03	300,23	
24	106,95	104,15	39	173,80	171,00	54	240,64	237,84	69	307,48	304,68	
25	111,41	108,61	40	178,25	175,45	55	245,10	242,30	70	311,94	309,14	
26	115,86	113,06	41	182,71	179,91	56	249,55	246,75	71	316,40	313,60	
27	120,32	117,52	42	187,16	184,36	57	254,01	251,21	72	320,85	318,05	
28	124,78	121,98	43	191,62	188,82	58	258,47	255,67				
29	129,23	126,43	44	196,08	193,28	59	262,92	260,12				
30	133,69	130,89	45	200,53	197,73	60	267,38	264,58				
31	138,15	135,35	46	204,99	202,19	61	271,83	269,03				
32	142,50	139,80	47	209,45	206,65	62	276,29	273,49				

Pulleys

Diameter	

Table 11		Pulleys for CONTI® SYNCHRODRIVE STD synchronous drive belts 3 mm tooth pitch, S 3M profile (measurement in mm)											
Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a		
20	19,10	18,34	35	33,42	32,66	50	47,75	46,99	65	62,07	61,31		
21	20,05	19,29	36	34,38	33,62	51	48,70	47,94	66	63,03	62,27		
22	21,01	20,25	37	35,33	34,57	52	49,66	48,90	67	63,98	63,22		
23	21,96	21,20	38	36,29	35,53	53	50,61	49,85	68	64,94	64,18		
24	22,92	22,16	39	37,24	36,48	54	51,57	50,81	69	65,89	65,13		
25	23,87	23,11	40	38,20	37,44	55	52,52	51,75	70	66,85	66,09		
26	24,83	24,07	41	39,15	38,39	56	53,48	52,72	71	67,80	67,04		
27	25,78	25,02	42	40,11	39,35	57	54,43	53,67	72	68,75	67,99		
28	26,74	25,98	43	41,06	40,30	58	55,39	54,63					
29	27,69	26,93	44	42,02	41,26	59	56,34	55,58					
30	28,65	27,89	45	42,97	42,21	60	57,30	56,54					
31	29,60	28,84	46	43,93	43,17	61	58,25	57,49					
32	30,56	29,80	47	44,88	44,12	62	59,21	58,45					
33	31,51	30,75	48	45,84	45,08	63	60,16	59,40					
34	32,47	31,71	49	46,79	46,03	64	61,12	60,36					

Table 12	Table 12 Pulleys for CONTI® SYNCHRODRIVE STD synchronous drive belts 5 mm tooth pitch, S 5M profile (measurement in mm)											
Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	Number of teeth z	Pitch diameter d _w	Outside diameter d _a	
12	19,10	18,14	28	44,56	43,60	44	70,03	69,07	60	95,49	94,53	
13	20,69	19,73	29	46,15	45,19	45	71,62	70,66	61	97,08	96,12	
14	22,28	21,32	30	47,75	46,79	46	73,21	72,25	62	98,68	97,72	
15	23,87	22,91	31	49,34	48,38	47	74,80	73,84	63	100,27	99,31	
16	25,46	24,50	32	50,93	49,97	48	76,39	75,43	64	101,86	100,90	
17	27,06	26,10	33	52,52	51,56	49	77,99	77,03	65	103,45	102,49	
18	28,65	27,69	34	54,11	53,15	50	79,58	78,62	66	105,04	104,08	
19	30,24	29,28	35	55,70	54,74	51	81,17	80,21	67	106,63	105,67	
20	31,83	30,87	36	57,30	56,34	52	82,76	81,80	68	108,23	107,27	
21	33,42	32,46	37	58,89	57,93	53	84,35	83,39	69	109,82	108,86	
22	35,01	34,05	38	60,48	59,52	54	85,94	84,98	70	111,41	110,45	
23	36,61	35,65	39	62,07	61,11	55	87,54	86,58	71	113,00	112,04	
24	38,20	37,24	40	63,66	62,70	56	89,13	88,17	72	114,59	113,63	
25	39,79	38,83	41	65,25	64,29	57	90,72	89,76				
26	41,38	40,42	42	66,85	65,89	58	92,31	91,35				
27	42,97	42,01	43	68,44	67,48	59	93,90	92,94				

Table 13	Table 13 Pulleys for CONTI® SYNCHRODRIVE STD synchronous drive belts 8 mm tooth pitch, S 8M profile (measurement in mm)												
Number of teeth z	Pitch diame- ter d _w	Outside diame- ter d _a	Number of teeth z	Pitch diame- ter d _w	Outside diame- ter d _a	Number of teeth z	Pitch diame- ter d _w	Outside diame- ter d _a	Number of teeth z	Pitch diame- ter d _w	Outside diameter d _a		
16	40,74	39,37	31	78,94	77,57	46	117,14	115,77	61	155,34	153,97		
17	43,29	41,92	32	81,49	80,12	47	119,68	118,31	62	157,88	156,51		
18	45,84	44,47	33	84,03	82,66	48	122,23	120,86	63	160,43	159,06		
19	48,38	47,01	34	86,58	85,21	49	124,78	123,41	64	162,97	161,60		
20	50,93	49,56	35	89,13	87,76	50	127,32	125,95	65	165,52	164,15		
21	53,48	52,11	36	91,67	90,30	51	129,87	128,50	66	168,07	166,70		
22	56,02	54,65	37	94,22	92,85	52	132,42	131,05	67	170,61	169,24		
23	58,57	57,20	38	96,77	95,40	53	134,96	133,59	68	173,16	171,79		
24	61,12	59,75	39	99,31	97,94	54	137,51	136,14	69	175,71	174,34		
25	63,66	62,29	40	101,86	100,49	55	140,06	138,69	70	178,25	176,88		
26	66,21	64,84	41	104,41	103,04	56	142,60	141,23	71	180,80	179,43		
27	68,75	67,38	42	106,95	105,58	57	145,15	143,78	72	183,35	181,98		
28	71,30	69,93	43	109,50	108,13	58	147,70	146,33					
29	73,85	72,48	44	112,05	110,68	59	150,24	148,87					
30	76,39	75,02	45	114,59	113,22	60	152,79	151,42					

Tolerances

Table 14 Outside diameter tol	erances
Outside diameter da mm	Tolerance mm
≤ 25	+ 0,05 0
> 25 - 50	+ 0,08 0
> 50 -100	+ 0,10 0
> 100 -175	+ 0,13 0
> 175 - 300	+ 0,15 0
> 300 - 500	+ 0,18 0
> 500	+ 0,20 0

Table 15 Axial runout tolerances									
Outside diameter da mm	Tolerance mm								
≦ 100	0,1								
> 100 -250	0,001 per mm outside diameter								
> 250	0,25 + 0,0005 per mm outside diameter								

Table 16 Radial runout tolerar	nces
Outside diameter d _a mm	Tolerance mm
≦ 200	0,13
> 200	0,13 + 0,0005 per mm outside diameter

Parallelism

Parallelism between the bore and teeth may not exceed the maximum deviation of 1 μm per millimetre of pulley width.

Draft

The maximum allowable draft is 1 $\mu m\,$ per millimetre of face width, but it must not exceed the permissible diameter tolerance.

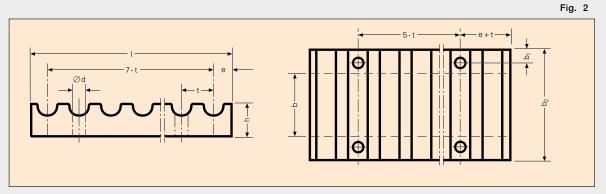
Pulleys

Clamp plates

CONTI® SYNCHRODRIVE synchronous drive belts that are used as openended power transmission components must be clamped with a positive fit at their ends. Clamp plates must have the corresponding tooth profile. The clamping screws should be positioned on both sides of the belt, and tightened in a uniform fashion.

Fig. 2 shows the type of clamp plate used. Dimensions for the standard type are given in Table 17.

Clamp plates for CONTI® SYNCHRODRIVE belt drives are available from your Mulco sales partner.

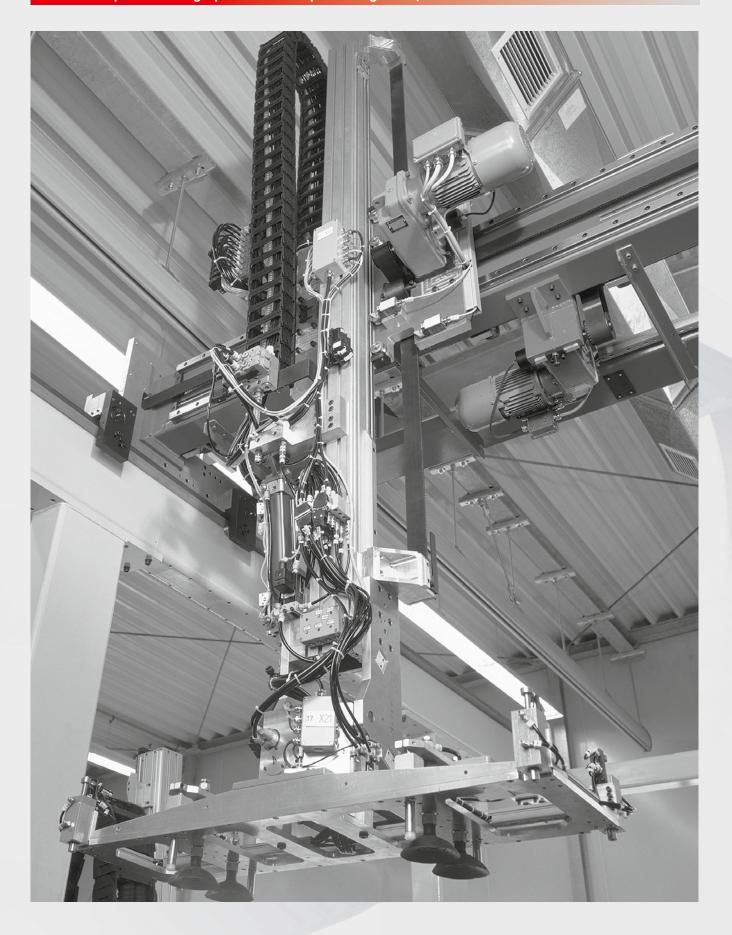


Clamp plate layout principle

Table 17 Clamp plate dimensions (in mm)											
T 11 51		HTD				STD					
Tooth profile		3M	5M	8M	14M	S 3M	S 5M	S 8M			
t			5,0	8,0	14,0		5,0	8,0			
l e			41,4	66,0	116,0		41,4	66,0			
			3,2	5,0	9,0		3,2	5,0			
h		8,0	15,0	22,0		8,0	15,0				
d			5,5	9,0	11,0		5,5	9,0			
b ₁			6,0	8,0	10,0		6,0	8,0			
b ₂ for synchronous drive belt width	10,00		28,0					28,0			
b mm	15,00		34,0	40,0			34,0	40,0			
	20,00			45,0				45,0			
	25,00		44,0				44,0				
	30,00			55,0				55,0			
	40,00				71,0						
	50,00			75,0				75,0			
	55,00				86,0						
	85,00			110,0	116,0			110,0			
	100,00				131,0						
	115,00				146,0						
	120,00				151,0						
	150,00				181,0						

Clamp plates for STD S 3M and HTD 3M are available on request.

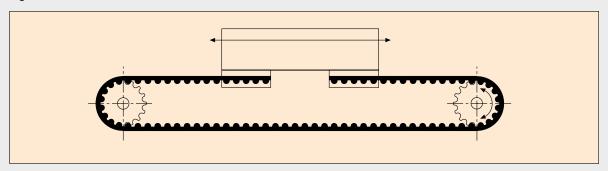
Glossery of symbols and terms, Drive calculation data, Examples of design procedure steps: Lifting drive, Linear drive



Calculation of synchronous belt drives

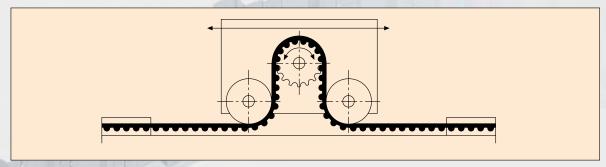
Calculations are based on drives fitted with CONTI® SYNCHRODRIVE synchronous drive belts. Drive design data are given in the following diagrams and tables. As so many factors influence belt performance, it is suggested that designers of complicated drives consult your Mulco sales Partner.

Fig. 3



Synchronous belt linear drive with 2 pulleys and no deflection

Fig. 4



Synchronous belt linear drive with 1 pulley and deflection idlers

Glossary of symbols, units and terms

Symbol	Unit	Definition	Symbol	Unit	Definition
а	mm	centre distance	m _{ges}	kg	total weight
Δa	mm	take up allowance	m _R	kg	weight of belt
a _b	m/s ²	acceleration	m _S	kg	weight of carriage
a _v	m/s ²	braking deceleration	m _{Sch}	kg	weight of pulley
b	mm	belt width	m _{Sch red}	kg	reduced weight of pulley
b _{err}	mm	calculated belt width	m _{spez}	kg/m	specific gravity of belt per
C _{spez}	N/mm	specific spring constant	·		m of length and mm of width
		per mm of belt length and	m _U	kg	weight of deflection idler
		mm of width	m _{U red}	kg	reduced weight of
c ₀		overall service factor			deflection idler
C ₁		teeth in mesh factor	М	N/m	torque
C _{1 max}		maximum value for teeth in	n	min−1	pulley speed
		mesh factor	n ₁	min−1	speed of driver pulley
C ₂		load factor	n_2	min ^{−1}	speed of driven pulley
C ₃		acceleration factor	Р	kW	power
d	mm	pulley/idler diameter	s _b	m	acceleration distance
d _a	mm	outside diameter of pulley	S _C	m	travel at v _{const}
d _F	mm	design-specific finished bore	S _{ges}	m	total travel
d _{min}	mm	minimum diameter of idler	S _V	m	braking distance
d _w	mm	pitch diameter of pulley	t	mm	pitch
d _{w1}	mm	pitch diameter of driver pulley	t _c	S	travel time at v _{const}
d _{w2}	mm	pitch diameter of driven pulley	U _w	mm	pitch circumference of pulley
f	Hz	natural frequency	V	m/s	belt speed
F _R	N	friction force	Z		number of teeth on the pulley
F _T	N	static belt tension	z _e		number of meshing teeth
F _{T max}	N	maximum belt tension dynamic	z _g		number of teeth on the
F _u	N	effective pull			large pulley
F _{u max}	N	maximum effective pull	Z _k		number of teeth on the
F _{u spez}	N	specific load on tooth flank			small pulley
F _V	N	belt installation tension	z _{min}	Contract of the second	minimum number of teeth
F _{zul}	N	allowable load on	z ₁		number of teeth on the
		tension member	4		driver pulley
g	9,81 m/s ²	gravitational acceleration	z_2		number of teeth on the
i		transmission ratio			driven pulley
Lf	m	free span length for	β	° (degrees)	arc of contact around the
		vibration excitation	46. 19		small pulley
L _w	mm	pitch length of belt	μ		coefficient of friction
L _{w max}	mm	maximum pitch length of belt			

Drive calculation data

The following pages contain all the data, formulae and tables needed when designing a new drive fitted with a CONTI® SYNCHRODRIVE synchronous drive belt. Tables for values which can easily be calculated using the formulae provided have been omitted.

The torques and effective pulls to be transmitted do not require any safety factors providing the maximum values are observed and the load is uniform. Corresponding factors must be applied in the event of fluctuating and alternating loads as well as with accelerating or braking processes.

Overall service factor c₀

The overall service factor c_0 takes into consideration the loads occurring under special operating conditions, and is the sum of load factor c_2 and acceleration factor c_3 .

$$c_0 = c_2 + c_3$$

Teeth in mesh factor c₁

The teeth in mesh factor c_1 considers the number of teeth ze of the small pulley z_k meshing with the teeth of the synchronous drive belt.

$$z_e = z_k \cdot \frac{\beta}{360}$$

Calculation of the arc of contact β is explained on page 21. The value for teeth in mesh factor c1 corresponds to the number of teeth in mesh z_e .

The following maximum values apply:

c_{2 max} = 6 for CONTI® SYNCHRODRIVE synchronous drive belts, type V

The minimum numbers of teeth z_{min} for pulleys that are to be taken into consideration when designing a drive are contained in Table 6 on page 11.

Load facor c2

Load factor c_2 is used to compensate for operating conditions. The factors given below are indicative values only.

Table 18 Load factor c ₂					
Operation conditions	Load factor c ₂				
Steady load	1,0				
Fluctuating load low	1,4				
Fluctuating load average	1,7				
Fluctuating load high	2,0				

Acceleration factor c3

The acceleration factor c_3 is applied if the step-up transmission ratio is > 1.24.

Table 19 Acceleration factor c ₃					
Transmission ration 1/i	Accelertion factor c ₃				
1,00 - 1,24					
1,25 - 1,74	0,1				
1,75 - 2,49	0,2				
2,50 - 3,49	0,3				
≥ 3,50	0,4				

Transmission ratio i

Transmission ratio i is obtained from the ratio of pulley speeds n_1 and n_2 or the number of teeth z_2 and z_1 or the pitch diameters of pulleys d_{w2} and d_{w1} .

$$i = \frac{n_1}{n_2} = \frac{z_2}{z_1} = \frac{d_{w2}}{d_{w1}}$$

Number of teeth \boldsymbol{z} and pitch diameter $\boldsymbol{d}_{\boldsymbol{w}}$ of the pulleys

The number of teeth z and the pitch diameter $d_{\rm W}$ of the pulleys are determined by means of pitch t of the chosen tooth profile.

$$z = \frac{\pi \cdot d_W}{t}$$
 $d_W = \frac{z \cdot t}{\pi}$ mm

Numbers of teeth, pitch and outside diameters of pulleys are contained in Tables 7 to 13 on pages 12 to 15.

Arc of contact β

For two-pulley drives, the arc of contact $\boldsymbol{\beta}$ around the small pulley is calculated as follows:

$$\beta = 2 \cdot \arccos \left[\begin{array}{c} t \cdot (z_g - z_k) \\ \hline 2 \cdot \pi \cdot a \end{array} \right] \, \, \text{°(Grad)}$$

For multiple-pulley drives, the arc of contact $\boldsymbol{\beta}$ has to be calculated in accordance with the given geometry.

Belt speed v

Belt speed v is derived from speed n in r.p.m., number of teeth z and pitch t in mm or pitch diameter d_w .

$$v = \frac{n \cdot z \cdot t}{60 \cdot 10^3} = \frac{n \cdot d_W \cdot \pi}{60 \cdot 10^3} \text{ m/s}$$

Center distance a

Center distance is calculated as follows for circular path drives with two pulleys and where transmission ratio i = 1:

$$a = \frac{L_W - z \cdot t}{2} mm$$

Where i does not equal 1, center distance a is approximated as below:

$$a \approx \frac{1}{4} \cdot \left[L_W - \frac{t}{2} \cdot (z_g + z_k) + \sqrt{\left[L_W - \frac{t}{2} \cdot (z_g + z_k)\right]^2 - 2 \cdot \left[\frac{t}{\pi} \cdot (z_g - z_k)\right]^2}\right] \ mm$$

Pitch length L_W

For a two-pulley drive, pitch length $L_{\rm W}$ of the synchronous drive belt is approximated as below:

$$L_{w} \approx 2 \cdot a + \frac{t}{2} \cdot (z_{g} + z_{k}) + \frac{\left[\frac{t}{\pi} \cdot (z_{g} - z_{k})\right]^{2}}{4 \cdot a} \quad mm$$

and calculated precisely as follows:

$$L_{w} = 2 \cdot a \cdot sin \frac{\beta}{2} \ + \frac{t}{2} \cdot \left[z_{g} + z_{k} + \left(1 - \frac{\beta}{180}\right) \cdot (z_{g} - z_{k})\right] \ mm$$

For linear and multiple-pulley drives, pitch length $L_{\rm w}$ is determined in accordance with the given geometry.

Effective pull F_u, torque M, power P

The following equations are used to calculate effective pull F_u, torque M and power P:

$$F_{U} = \frac{P \cdot 10^{3}}{v} = \frac{M \cdot 2 \cdot 10^{3}}{d_{W}} N$$

$$= \frac{P \cdot 9,55 \cdot 10^{3}}{n} = \frac{F_{U} \cdot d_{W}}{2 \cdot 10^{3}} Nm$$

$$P = \frac{M \cdot n}{9,55 \cdot 10^{3}} = \frac{F_{U} \cdot v}{10^{3}} kW$$

Drive calculation data

Belt width b

Belt width b is calculated from the effective pull F_u to be transmitted, the specific load on tooth flank $F_{u\ spez}$ as well as the service factor c_0 and the teeth in mesh factor c_1 .

$$b_{err} = \frac{F_u \cdot c_0 \cdot 10}{F_{u,spez} \cdot c_1} \quad mm$$

Values for the specific load on tooth flank $F_{u \; spez}$ can be taken from Figs. 6 to 7 on pages 24 and 26.

Once the belt standard width b has been determined, it is necessary to check the tension member load.

Permissible tension member loads F_{zul} for synchronous drive belts with standard widths are contained in Tables 20 and 22 on pages 25 and 27. The following rule applies:

$$F_{zul} \ge F_{T max} \cdot c_0 N$$

The next section explains how to determine the dynamic belt tension ${\rm F}_{\rm T\ max}.$

Belt installation tension F_V

Tensioning of the belt is a decisive factor affecting the reliability, performance and life of a synchronous belt drive.

Calculation

For linear drives, installation tension is calculated as the belt tension. The following rule applies to the static belt tension F_T :

$$F_T \ge F_{u \text{ max}} N$$

Maximum belt tension $F_{T\ max}$ occurring in the dynamic state is derived from

$$F_{T max} = F_{T} + F_{u max} N$$

With circular path drives, installation tension is usually given as shaft load F_{ν} . The following equation applies:

$$F_v = F_u \cdot \sin \frac{\beta}{2}$$
 N

Adjusting installation tension F_T via the takeup allowance

On linear drives, installation tension is adjusted via belt elongation. The takeup allowance a in mm is derived from the belt tension F_T , the belt dimensions L_w and b as well as the spring constants c_{spez} .

For linear drives as shown in Fig. 3 on page 18

$$\Delta a = \frac{F_T \cdot L_W}{2 \cdot c_{\text{spez}} \cdot b}$$
 mm

For linear drives as shown in Fig. 4 on page 18

$$\Delta a = \frac{F_T \cdot L_W}{c_{\text{spez}} \cdot b}$$
 mm

The values for the spring constants c_{spez} can be taken from Tables 21 and 23 on pages 25 and 27.

Adjusting installation tension via the frequency measurement method

Installation tension on linear drives can also be adjusted by measuring the natural frequency of a vibrating belt span. It must be remembered, however, that measurable vibrations are only obtainable from a free span length $L_{\rm f}$ up to a certain length.

See also our calculation examples.

$$f = \sqrt{\frac{F_T}{4 \cdot m \cdot L_{f^2}}}$$

Selecting the tooth profile

A suitable tooth profile is selected from Fig. 5 by locating the point at which the effective pull to be transmitted intersects with the possible belt width. The belt with the greatest power transmitting capacity should be selected. In borderline cases, it is recommended that the smaller profile is taken as a basis for drive design calculation.

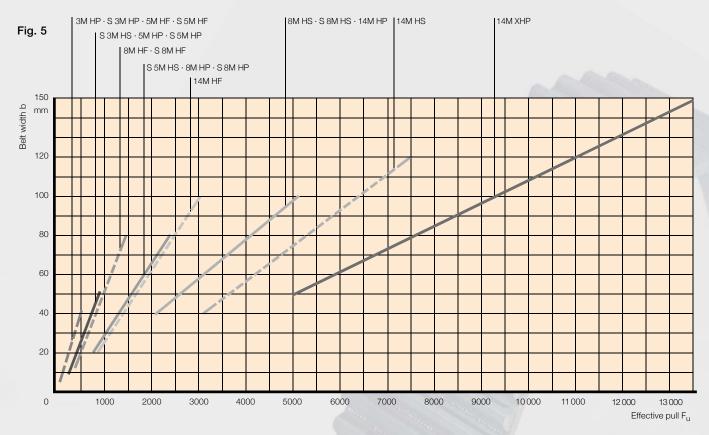


Diagram for selecting CONTI® SYNCHRODRIVE synchronous drive belts

Specific load on tooth flank $F_{u \text{ spez}}$, tension member load F_{zul} , specific spring constant c_{spez}

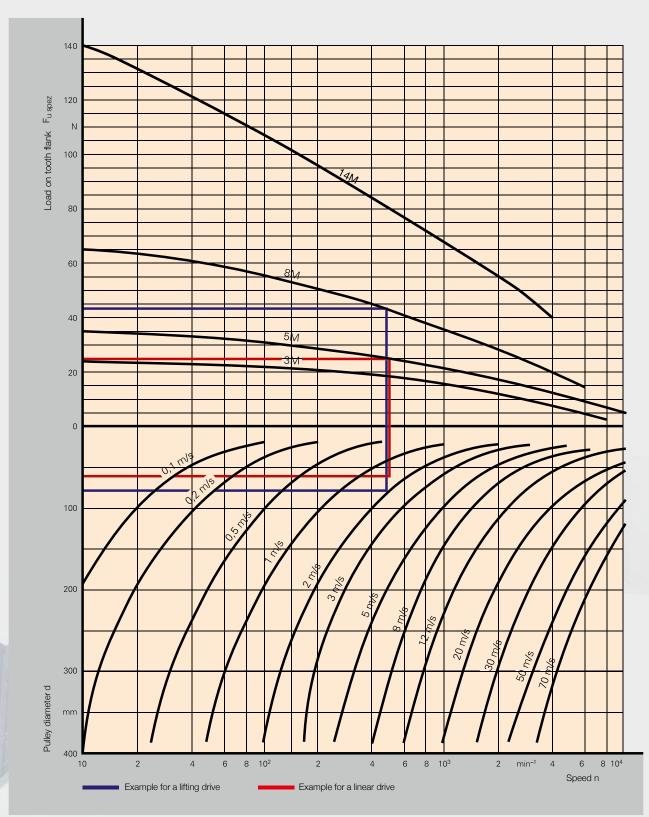
The values required for the specific load on tooth flank, tension member load and specific spring constant in order to arrive at a precise drive design can be taken from the diagrams and tables on the following pages.

The specific load on tooth flank $F_{u\;spez}$ can be taken from Figs. 6 and 7 after calculating speed n in r.p.m. from the

given belt speed v in m/s and the pulley diameter d_w in mm for the corresponding profile.

Tension member load F_{zul} in N is given in Tables 20 and 22. Tables 21 and 23 show the specific spring constant c_{spez} in N/mm for calculating takeup allowance Δa .

Fig. 6



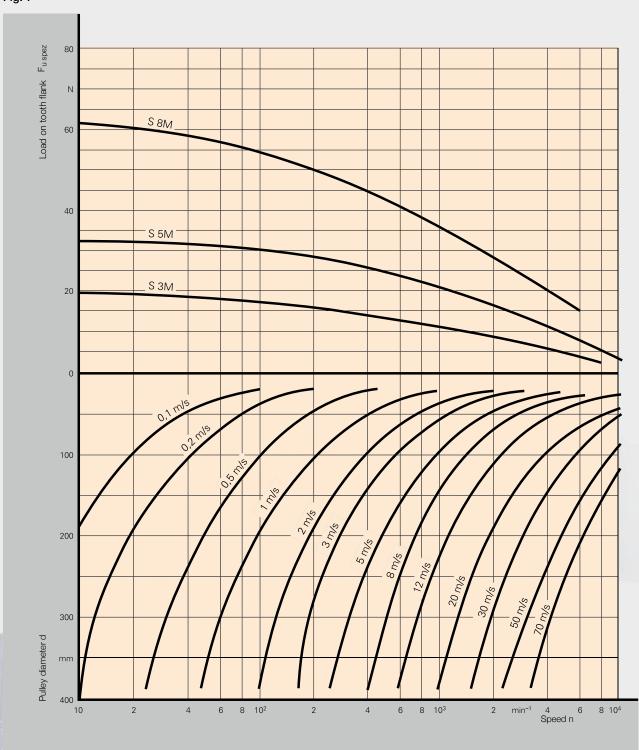
Specific load on tooth flank $F_{u\ spez}$ in N per 10 mm belt width and per meshing tooth for CONTI® SYNCHRODRIVE HTD synchronous drive belts 3M, 5M, 8M, 14M

Tab. 20 Allowable tension member load* F _{zul} in N at 0.4% elongation														
CONTI® SYNCHRODRIV	E HTD	synchro	onous d	rive bel	ts – 3M,	5M, 8M	, 14M							
Tooth profile Type/Version		3M HP	5M HF	HP	V-HF	8M HF	НР	HS	V-HF	14M HF	НР	HS	XHP	V-HF
Belt width b mm	5	150	150											
Deit Width 5 min	10	300	300	650		650								
	15	450	450	975		975	1800	3150						
	20	600	600	1300	300	1300	2400	4200		2400				
	25	750	750	1625	375	1625	3000	5250	750	3000	5250			
	30	900	900	1950	450	1950	3600	6300	900	3600	6300	7500		1800
	40	1200	1200	2600	600	2600	4800	8400	1200	4800	8400	10000	19000	2400
	50	1500	1500	3250	750	3250	6000	10500	1500	6000	10500	12500	23800	3000
	55					3575	6600	11550	1650	6600	11550	13750	26100	3300
	85					5525	10200	17850	2550	10200	17850	21250	40400	5100
	100			·		6500	12000	21000	3000	12000	21000	25000	47600	6000
	115			·							24150	28750	54700	
	120										25200	30000	57100	
	150												71400	

^{*} The breaking load equals about factor 4 in relation to the admissible load on the tension members.

Tab. 21 Specifi	Tab. 21 Specific spring constant c _{spez} in N/mm										
CONTI® SYNCH	IRODRIVE	HTD sync	hronous di	rive belts -	3M, 5M, 8N	Л, 14M					
Tooth profile Type/Version		3M HP	5M HF	HP	8M HF	НР	HS	14M HF	HP	HS	XHP
C _{Spez}	N/mm	7,5·10 ³	7,5·10 ³	20·10 ³	20·10 ³	35·10 ³	53·10 ³	35·10 ³	53·10 ³	63·10 ³	120·10 ³

Fig. 7



Specific load on tooth flank $F_{u\ spez}$ in N per 10 mm belt width and per meshing tooth for CONTI® SYNCHRODRIVE STD synchronous drive belts S 3M, S 5M, S 8M

Tab. 00. Allowable tension		ad* F is	N at 0 40/	alangatian						
Tab. 22 Allowable tension CONTI® SYNCHRODRIVE S										
Tooth profile	Synchro	S 3M	S 5M	SIVI, S SIVI, S	5 OIVI		S 8M			
Type/Version		HP	HF	HP	HS	V-HF	HF	HP	HS	V-HF
Belt width b mm	5	150	150							
	10	300	300	650	1200		650			
	15	450	450	975	1800		975	1800	3150	
	20	600	600	1300	2400	300	1300	2400	4200	
	25	750	750	1625	3000	375	1625	3000	5250	750
	30	900	900	1950	3600	450	1950	3600	6300	900
	50	1500	1500	3250	6000	750	3250	6000	10500	1500
	85						5525	10200	17850	2550
	100						6500	12000	21000	3000
	115								24150	
	120								25200	

^{*} The breaking load equals about factor 4 in relation to the admissible load on the tension members.

Tab. 23 Specific spring constant c _{spez} in N/mm								
CONTI® SYNCH	HRODRIVE S	TD synchronou	s drive belts - S	3M, S 5M, S 8	М			
Tooth profile		S 3M	S 5M			S 8M		
Type/Version		HP	HF	HP	HS	HF	HP	HS
C _{spez}	N/mm	7,5-10 ³	7,5·10³	20·10³	35·10³	20·10³	35·10³	53·10³

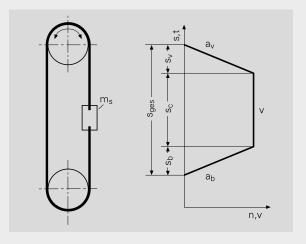
Examples of design procedure steps: Lifting drive

Fig. 8

Example

Determine the CONTI® SYNCHRODRIVE synchronous drive belt needed for a lifting drive with the following specification:

Pitch length of the belt $L_W = 6000 \text{ mm}$ Pitch diameter of the pulleys $d_w = 80 \text{ mm}$ $m_s = 45 \text{ kg}$ Mass of the carriage Friction force $F_R = 50 N$ Travel at v_{const} $s_c = 2.0 \text{ m}$ = 2 m/sTravel speed Acceleration $a_b = 8.0 \text{ m/s}^2$ $a_V = 8.0 \text{ m/s}^2$ Braking deceleration



Lifting drive - principle and motion diagram

Calculate linear monementum

Acceleration distance

$$s_b = \frac{v^2}{2 \cdot a_b}$$

$$s_b = \frac{2^2}{2 \cdot 8} = 0.25 \text{ m}$$

Braking distance

$$s_{V} = \frac{V^{2}}{2 \cdot a_{V}}$$

$$s_V = \frac{2^2}{2 \cdot 8} = 0.25 \text{ m}$$

Total travel

$$s_{ges} = s_b + s_c + s_v$$

$$s_{ges} = 0.25 + 2.0 + 0.25 = 2.5 \text{ m}$$

Pulleys

Pitch diameter d_w from Table 9 on page 13

Design-specific finished bore

Mass of the pulleys according to manufacturer's specification

Pulley designation

Selected: $d_w = 81.49 \text{ mm}$ z = 32

 $d_F = 40 \text{ mm}$

 $m_{Sch} = 1,53 \text{ kg}$

HTD Pulley P 32 – 8M – 30

Select tooth profile

$$F_u = m_s \cdot a_b + m_s \cdot g$$

Select profile Selected:

$$F_{IJ} = 45 \cdot 8 + 45 \cdot 9,81 = 801,5 \text{ N}$$

CONTI® SYNCHRODRIVE synchronous drive belt profile 8M width 30 mm type M HP

Precisely determine the maximum effective pull to be transmitted

Mass of carriage m_s

 $m_s = 45 \text{ kg}$

Mass of belt m_R

 $m_R = m_{spez} \cdot b \cdot L_w$

Weight from Table 1 on page 7

 $m_R = 6.32 \cdot 10^{-3} \cdot 30 \cdot 6 = 1.14 \text{ kg}$

Reduced mass of the pulleys

$$m_{Sch red} = \frac{m_{Sch}}{2} \cdot \left(1 + \frac{d_F^2}{d_a^2}\right)$$

 $m_{Sch red} = \frac{1,53}{2} \cdot \left(1 + \frac{40^2}{80,12^2}\right) = 0,96 \text{ kg}$

Total mass

 $m_{ges} = m_s + m_R + M_{Sch red}$

 $m_{qes} = 45 + 1,14 + 0,96 = 47,1 \text{ kg}$

Maximum effective pull to be transmitted

 $F_{u \text{ max}} = m_{qes} \cdot a_b + m_s \cdot g + F_R$

 $F_{u \text{ max}} = 47,1 \cdot 8 + 45 \cdot 9,81 + 50 = 868 \text{ N}$

Calculation factors

Tooth in mesh factor c₁ from page 20

Load factor for average fluctuation load

c₂ from Table 18 on page 20

 $\begin{array}{l} \text{Acceleration factor c_3} \\ \text{from Table 19 on page 20} \end{array}$

Overall service factor

 $C_0 = C_2 + C_3$

 $c_1 = 12$

 $c_0 = 1.7 + 0 = 1.7$

Determine belt width in accordance with allowable flank load

$$b_{err} = \frac{F_{u \; max} \cdot c_0 \cdot 10}{F_{u \; spez} \cdot c_1}$$

 $F_{u \text{ spez}}$ from Table 6 on page 24

 $b_{err} = \frac{868 \cdot 1,7 \cdot 10}{43 \cdot 12} = 29 \text{ mm}$

Requirement

 $b > b_{err}$

Next grater belt width b from Table 2 on page 7

Selected: b = 30 mm

Belt installation tension

The following applies for linear drives:

 $F_T \ge F_{u \text{ max}}$

Selected: $F_T = 900 \text{ N} > 868 \text{ N}$

Max. belt tension dynamic

 $F_{T \text{ max}} = F_{T} + F_{u \text{ max}}$

 $F_{T \text{ max}} = 900 + 868 = 1768 \text{ N}$

Takeup allowance for linear drives

$$\Delta a = \frac{F_T \cdot L_W \cdot 10^3}{2 \cdot c_{\text{spez}} \cdot b}$$

 $\rm c_{\rm spez}$ from Table 21 on page 25

$$\Delta a = \frac{900 \cdot 6000}{2 \cdot 35 \cdot 30} = 2,6 \text{ mm}$$

Alternatively it is possible to install the pretension via frequency measurement method. Therefore it is necessary to move the clamp end nearby (about 1 m) to the deflection point. This freely chosen span length can be used for calculation and measurements. See also page S. 22.

Free span length

Selected: $L_f = 1 \text{ m}$

Weight m per m length

 $m = m_{\text{Spez}} \cdot b$ m_{Spez} from Table 1, Page 7

$$m = 6,32 \cdot 10^{-3} \cdot 30 = 0,19 \ \frac{kg}{m}$$

Belt tension frequency

$$f = \sqrt{\frac{F_T}{4 \cdot m \cdot L_{f^2}}}$$

$$f = \sqrt{\frac{900}{4 \cdot 0,19 \cdot 1^2}} = 34 \text{ Hz}$$

The belt has the right pretension when the measured frequency is the same as the calculated frequency.

Check allowable tension member load

 F_{zul} = from Table 20, Page 25

Requirement

 $F_{zul} \ge F_{Tmax} \cdot c_0$

 $F_{zul} = 3600N$

 $3600 > 1768 \cdot 1,7$

3600 > 3006

Requirement is fulfilled, i.e. the allowable tension member load is greater than the maximum belt tension taking the service factor into consideration.

Design choice:

CONTI® SYNCHRODRIVE HTD synchronous drive belt M 6 – 8M – 30 HP

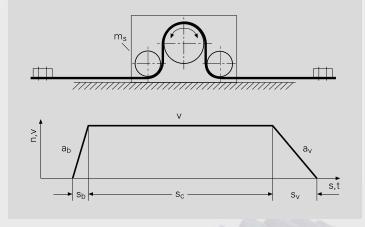
Examples of design procedure steps: Linear drive

Fig. 9

Example

Determine the CONTI® SYNCHRODRIVE synchronous drive belt needed for a linear drive with the following specification:

Pitch length of the belt	L_{W}	=	8000 mm
Pitch diameter of the pulley	d_{w}	=	80 mm
Idler diameter	d	<	60 mm
Mass of carrige	m_s	=	30 kg
Coefficient of friction	μ	=	0,6
Travel time	t _c	=	3 s
Travel at v _{const}	s_{c}	=	5,0 m
Acceleration distance	s _b	=	0,5 m
Braking distance	s_V	=	1,5 m



Linear drive - principle and motion diagram

Calculate acceleration and braking deceleration

Travel speed

$$v = \frac{s_{_{\tiny C}}}{t_{_{\tiny C}}}$$

$$v = \frac{5}{3} = 1,67 \text{ m/s}$$

Acceleration

$$a_b = \frac{v^2}{2 \cdot s_b}$$

$$a_b = \frac{1,67^2}{2 \cdot 0.5} = 2,79 \text{ m/s}^2$$

Braking deceleration

$$a_V = \frac{V^2}{2 \cdot s_V}$$

$$a_V = \frac{1,67^2}{2 \cdot 1,5} = 0,93 \text{ m/s}^2$$

Select tooth profile

Approximate calculation of effective pull to be transmitted

$$F_u = m_s \cdot a_b + m_s \cdot g \cdot \mu$$

Select profile from

Fig. 5,

page 23

$$F_u = 30 \cdot 2,79 + 30 \cdot 9,81 \cdot 0,6 = 260 \text{ N}$$

Selected:

CONTI® SYNCHRODRIVE synchronous drive belt, profile 5M

width 30 mm

type M HP

Pulleys

Pitch diameter d_w from Table 8, Page 12

Design-specific finished bore

Mass of the pulleys according to manufacturer's specification

Pulley designation

Selected: $d_W = 60,48 \text{ mm}$ z = 38

 $d_F = 30 \text{ mm}$

 $m_{Sch} = 0,47 \text{ kg}$

HTD Pulley P 38 – 5M – 15

Deflector idlers

Diameter

Finished bore

Mass of deflectors idlers according to maufacturer's specification

Selected: $d_a = 55 \text{ mm}$

 $d_F = 30 \text{ mm}$

 $m_U = 0,43 \text{ kg}$

Precisely determine the maximum effective pull to be transmitted

Reduced mass of the idlers

$$m_{U \text{ red}} = \frac{m_U}{2} \cdot \left(1 + \frac{d_F^2}{d^2}\right)$$

$$\begin{aligned} F_{u\;max} &= (m_S + m_{Sch} + 2 \cdot m_U) \cdot a_b \\ &\quad + 2 \cdot m_{U\;red} \cdot a_b \\ &\quad + (m_S + m_{Sch} + 2 \cdot m_U) \cdot g \cdot \mu \end{aligned}$$

$$m_{U \text{ red}} = \frac{0.43}{2} \cdot \left(1 + \frac{30^2}{55^2}\right) = 0.28 \text{ kg}$$

$$\begin{aligned} \mathsf{F_{u\;max}} &= (30 \, + \, 0.47 \, + \, 2 \cdot 0.43) \cdot 2.79 \\ &+ \, 2 \cdot 0.28 \cdot 2.79 \\ &+ \, (30 \, + \, 0.47 \, + \, 2 \cdot 0.43) \cdot 9.81 \cdot 0.6 \\ &= \, 273 \; \mathsf{N} \end{aligned}$$

Calculation factor

Tooth in mesh factor c₁ page 20

Load factor for low-fluctuation load c₂ from Table 18, Page 20

Acceleration factor c₃ from Table 19, Page 20

Overall service factor $c_0 = c_2 + c_3$

$$c_1 = 12$$

$$c_2 = 1,4$$

$$c_3 = 0$$

$$c_0 = 1,4 + 0 = 1,4$$

Determine belt width in accordance with allowable flank load

$$b_{err} = \frac{F_{u \; max} \cdot c_0 \cdot 10}{F_{u \; spez} \cdot c_1}$$

 $F_{u \text{ spez}}$ from Fig. 6, Page 24 Requirement $b > b_{err}$

Next greater belt width b from Table 2, Page 7

$$b_{err} = \frac{273 \cdot 1,4 \cdot 10}{25 \cdot 12} = 13 \text{ mm}$$

Selected: b = 15 mm

Belt installation tension

The following applies for linear drives:

 $F_T \geqq F_{u \; max}$

Max. belt tension dynamic

$$F_{T max} = F_{T} + F_{u max}$$

Takeup allowance for linear drives

$$\Delta a = \frac{F_T \cdot L_W}{c_{spez} \cdot b}$$

c_{spez} from Table 21, Page 25

Selected:

$$F_T = 300 \text{ N} > 273 \text{ N}$$

$$F_{T \text{ max}} = 300 \text{ N} + 273 = 573 \text{ N}$$

$$\Delta a = \frac{300 \cdot 8000 \text{ mm}}{20 \cdot 10^3 \cdot 15} = 8.0 \text{ mm}$$

Alternatively it is possible to install the pretension via frequency measurement method. Therefore it is necessary to move the clamp end nearby (about 1 m) to the deflection point. This freely chosen span length can be used for calculation and measurements. See also page 22.

Free span length

Weight m per m length

$$m = m_{spez} \cdot b$$

m_{spez} from Table 1, Page 7

Selected: $L_f = 1m$

$$m = 4,06 \cdot 10^{-3} \cdot 15 = 0,0609 \frac{kg}{m}$$

Belt tension frequency

$$f = \sqrt{\frac{F_T}{4 \cdot m \cdot L_{f^2}}}$$

$$f = \sqrt{\frac{300}{4 \cdot 0,0609 \cdot 1^2}} = 35 \text{ Hz}$$

The belt has the correct pretension when the

= 35 Hz measured frequency is the same as the calculated frequency.

Check allowable tension member load

 F_{zul} = from Table 20, Page 25

Requirement: $F_{zul} \ge F_T \max \cdot c_0$

 $F_{zul} = 975 \text{ N}$

 $975 > 573 \cdot 1,4$ 975 > 802 Requirement is fulfilled, i. e. the allowable tension member load is greater than the maximum belt tension taking the service factor into consideration.

Design choice

CONTI® SYNCHRODRIVE HTD synchronous drive belt M8 – 5M – 15 HP

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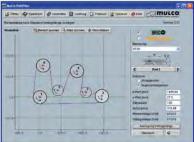
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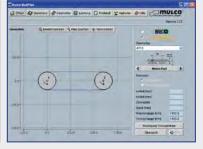
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Polyurethane timing belt welder

Welds what belongs together

The portable TSG 4 welder - ready for a quick change

Even top-quality products will eventually wear out. The same applies to polyurethane timing belts which, from time to time, need to be replaced. We designed the portable TSG welder to assist you in replacing drive units that take a lot of mounting effort and are difficult to access due to upstream machine components. The portable TSG welder is easy to operate and allows you to weld polyurethane timing belts onsite, immediately in or at the machine. The TSG 4 welding unit is available in two versions: for belt widths up to 50 mm and for belt widths up to 100 mm.



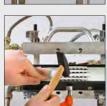
One welder, many benefits

- Suitable for all timing belt profiles
- Short machine downtimes
- Easy to operate
- Flexible through long power cords
- Welds and cools down in as little as about 30 minutes
- Air-cooled, no water supply required
- Powerful heater output

Standard package

- Welder with belt-specific, replaceable weld face
- Control unit for automatic welding and cooling down
- Control unit and welder connect by metal-reinforced cable
- Transport case with tools







Technical data TSG 4 - 50

Operating voltage: 230 V/50 Hz Power consumption: 1.2 kW

Welder dimensions:

W 240 mm x H 220 mm x D 170 mm

Welder weight: approx. 7.5 kg*

Control unit dimensions:

Type-III/TSG MR 10

W 350 mm x H 166 mm x D 355 mm

Control unit weight: approx. 9.0 kg

Carrying case weight: approx. 6.0 kg

Technical data TSG 4 - 100

Operating voltage: 230 V/50 Hz

Power consumption: 2 kW

Welder dimensions:

W 240 mm x H 220 mm x D 220 mm

Welder weight: approx. 9.5 kg*

Control unit dimensions:

Type-III/TSG MR 10

B 350 mm x H 166 mm x D 355 mm

Control unit weight: approx. 9.0 kg

Carrying case weight: approx. 6.0 kg

* including connecting leads



Special accessories

- Hydraulic punch
- Weld jigs for all standard belt profiles
- Punch box
- All units available separately

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